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The pre-design orientation needed to be considered in this study. In relation to the trunnion, it was important to identify the position in order to evaluate the variability of the distance between the trunnion and the head of the prosthesis. To achieve this, three dimensional (3D) models of the head, the trunnion and the head with the trunnion were performed. All models were created in Netfabb 2018 in the following steps: first the head model was created, using the reference size for a large head head size of 40 mm (that corresponds to the polyurethane cover), and the cups were positioned in the frontal view. The trunnion model was created with the same size as the cup. The trunnion, which corresponds to the shell formed on the trunnion of the prosthesis, was fixed by an hexagonal bar. The hexagonal bar was fixed in the frontal view of the head using the bolt and nut technique. The head was fixed to the hexagonal bar. When the angles between the components were obtained, the prosthesis was oriented and fixed to the pelvic side (Figure 8 and Figure 9) ([Figure 10](#f02){ref-type="fig"}). Fully-CAD-based design represents the state-of-the-art for manufacturing. This approach allows the designer to work with only the design rules for the part that have been calculated, rather than having to apply all the many design rules in a non-CAD environment to generate a part. Once the CAD model is generated and exported, the material is added by the additive manufacturing process, usually by layering the material to create a 3D-print. The benefits of fully-CAD-based design include improved safety, efficiency and ergonomics. However, fully CAD-based manufacturing also presents the designer and manufacturer with numerous technical challenges, such as part porosity and surface smoothness, with the latter in particular being a key factor in the additive manufacturing process. Fully CAD-based manufacturing also has a reliance on the CAD model, which by its nature is not perfect and requires additional generation of a CAD model from the physical prototype. This additional step in the process of fully CAD-based manufacturing can be time consuming and increases the cost of manufacturing, and hence can add to the barriers to adoption (Bakir, Sperl, &

Li, 2016 ; Palant, & Gruhl, 2015).

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One of the most sophisticated uses of hybridisation currently exists in medicine. The development of organs through hybridisation of tissue-engineered organs is the current challenge of tissue engineering. The authors in this study utilise a hybridisation and co-culture of fetal bowel and bladder cells, using a hybridisation process in which the cells are transferred from the foetus to the bladder, where they develop into a fully formed neobladder (Lim et al., 2016). This concept also allows the transfer of organ growth potential, through the integration of foetal cells into the adult bladder, enabling the induction of regeneration (Lim et al., 2016). This form of hybridisation is limited to transferring material between two distinct organs, and has not utilised the full potential of hybridisation as a simultaneous additive manufacturing process. The addition of stimuli prior to and throughout hybridisation could expand hybridisation to encompass the dynamic interaction of multiple tissues, and the transfer of growth potential. Although the gap between hybridisation and the ability to truly create an organ or component through hybridisation is large, the introduction of concepts of In-situ DfAM may provide a viable alternative. Current additive manufacturing platforms are not able to incorporate stimuli which can stimulate material to allow the initiation of the entire 3-D formation, and the activation of synthetic materials is limited to an initial stimulus. This is highlighted in Figures 4 (a) and 4 (b), where the green highlight represents the current state of material activation, where the material is activated by the stimulus of fusion. By increasing the number of stimuli that can be introduced into a material during manufacture, the list of potential responses will expand. In addition to the stimuli introduced into the material, the temporal range that they can be introduced is limited by the speed of manufacture; the faster the manufacture is, the greater the range of stimuli, and vice versa. The introduction of In-situ DfAM would allow the stimulus to vary over time, and in any direction. The challenge in the implementation of such a process would be in the ability to focus the addition of material to specific areas, whilst simultaneously activating a response within the structure. Whilst this is technically possible, the complexity of the manufacturing process would require significant research and development to current technologies. 5ec8ef588b

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